

Competing risks models and time-dependent effects

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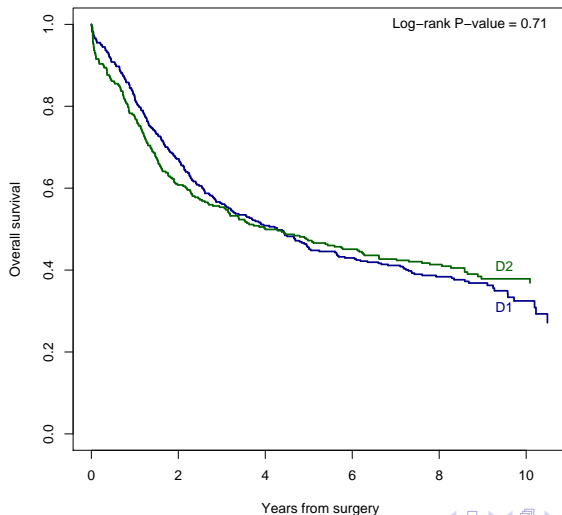
Dutch Gastric Cancer Trial

- ▶ Randomized clinical trial for gastric cancer patients
- ▶ 711 patients randomized between D1-dissection (380) and D2-dissection (331)
- ▶ D1-dissection: limited lymph-node dissection
 - ▶ Standard in Western Europe and America
- ▶ D2-dissection: more extensive lymph-node dissection
 - ▶ Standard in Japan
 - ▶ More surgical complications, more hospital deaths
 - ▶ Better overall survival in the lung run?
- ▶ Median follow-up: 9.1 years



Kaplan-Meier survival curves

Overall survival



Time-fixed Cox regression

- ▶ Suppose single covariate Z , say treatment
- ▶ $Z = 0$, placebo or standard treatment, here D1
- ▶ $Z = 1$, experimental treatment, here D2
- ▶ Hazard rate given by

$$\lambda(t | Z) = \lambda_0(t) \exp(\beta Z)$$

- ▶ $\lambda_0(t)$ is hazard rate corresponding to D1, $\lambda_1(t)$ to D2
- ▶ Proportional hazards assumption: ratio of hazards $\lambda_1(t)/\lambda_0(t) = \exp(\beta)$, independent of t

Time-dependent Cox regression

- ▶ Hazard rate given by

$$\lambda(t|Z) = \lambda_0(t) \exp(\beta_F Z + \beta_T Z f(t))$$

- ▶ β_F : time-fixed regression coefficient
- ▶ β_T : time-dependent regression coefficient
- ▶ Hazard ratio now varies with t

$$HR(t) = \frac{\lambda_1(t)}{\lambda_0(t)} = \exp(\beta_F + \beta_T f(t))$$

- ▶ Can test hypothesis $\beta_T = 0$; $\beta_T \neq 0$ indicates time-dependent treatment effect, violation of proportional hazards assumption

Applied to the Dutch Gastric Cancer Trial

- ▶ Take $f(t) = \log(t + 1)$:

	coefficient	standard error	P-value
treatment	0.760	0.261	0.0036
time*treatment	-0.273	0.084	0.0011

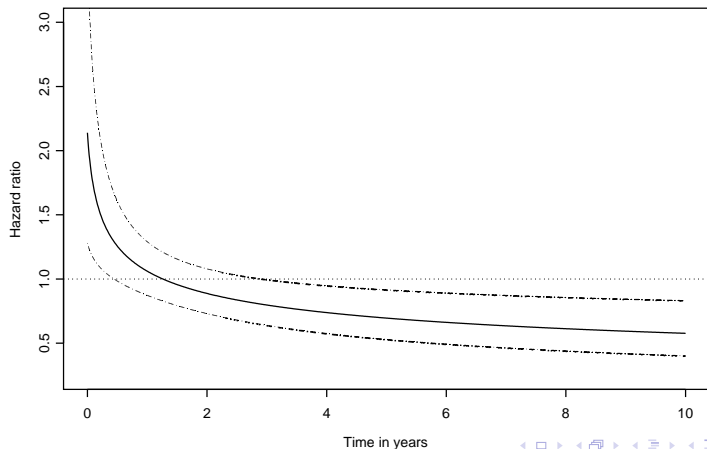
- ▶ Significant interaction of time by treatment;
- ▶ Indicates that proportional hazards assumption is violated;
- ▶ "Hazard ratio" (HR) will vary over time, according to

$$HR(t) = \exp(0.760 - 0.273 * \log(t + 1)) ;$$

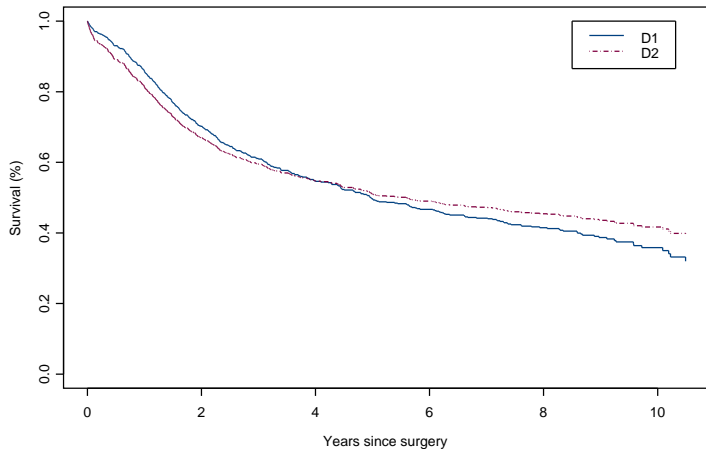
- ▶ $se(\log(HR(t))) =$
 $\sqrt{\text{var}(\hat{\beta}_F) + \text{var}(\hat{\beta}_T)f^2(t) + 2\text{cov}(\hat{\beta}_F, \hat{\beta}_T)f(t)}.$

Hazard ratio over time

Hazard ratio of D2 with respect to D1:



Fitted



Competing risks point of view

- ▶ So far we have looked at **overall** survival
- ▶ Cause of death also recorded

	Gastric cancer	Other causes
D1 ($n = 380$)	178 (47 %)	74 (19 %)
D2 ($n = 331$)	121 (37 %)	72 (22 %)

Competing risks

- ▶ Death due to different causes (competing risks)
- ▶ We observe
 - ▶ Time of death T
 - ▶ Cause of death D (1=cancer, 2=other, 0=censoring)
- ▶ Death of one cause precludes death of other cause
- ▶ Fundamental concept in competing risks models: the **cause-specific hazard** function

$$\lambda_k(t) = \lim_{\Delta t \downarrow 0} \frac{P(t \leq T < t + \Delta t, D = k \mid T \geq t)}{\Delta t}$$

- ▶ Cumulative cause-specific hazard

$$\Lambda_k(t) = \int_0^t \lambda_k(s) ds$$

Total and relative hazards

▶ Total hazard

$$\lambda_{\bullet}(t) = \sum_{k=1}^K \lambda_k(t)$$

▶ Relative hazard

$$\pi_k(t) = \frac{\lambda_k(t)}{\lambda_{\bullet}(t)}$$

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$$S(t) = \exp(-\Lambda_{\bullet}(t))$$

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- ▶ Relative hazard drives cause of death (given death at t)

Cumulative incidence functions

- ▶ **Cumulative incidence function**, $I_k(t)$, is defined as the probability of failing from cause k before time t

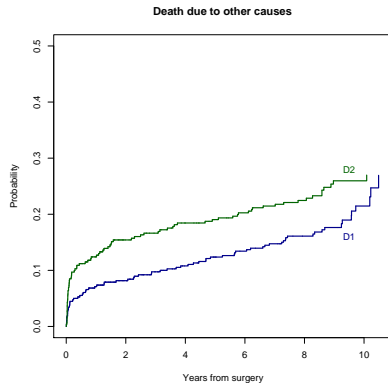
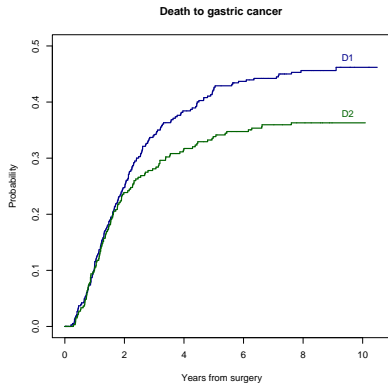
$$I_k(t) = P(T \leq t, D = k) = \int_0^t \lambda_k(s) S(s) ds$$

- ▶ Estimation of $I_k(t)$ by replacing hazards by estimates in above formula
- ▶ Don't use naive Kaplan-Meier estimator; is estimating

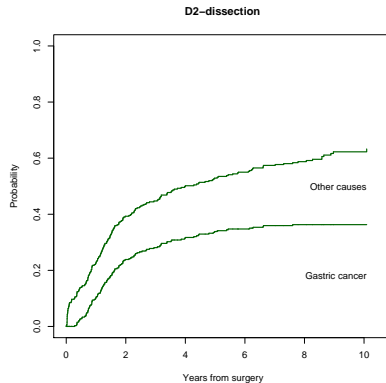
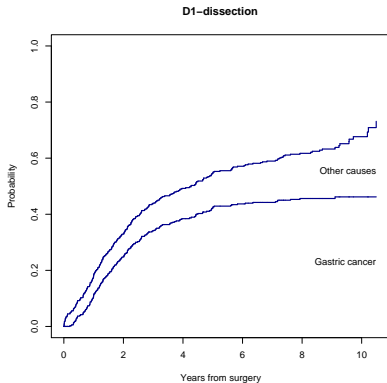
$$1 - S_k(t) = \int_0^t \lambda_k(s) S_k(s) ds ,$$

rather than $I_k(t)$

Cumulative incidence curves



Organized differently (stacked)



Regression on cause-specific hazards

- ▶ $\lambda_k(t | Z)$: cause-specific hazard of cause k of a subject with treatment Z (with $Z=0$ (D1) or 1 (D2)) given by

$$\lambda_k(t | Z) = \lambda_{k,0}(t) \exp(\beta_k Z) ,$$

with

- ▶ $\lambda_{k,0}(t)$ is the baseline (D1) cause-specific hazard of cause k
- ▶ β_k represents the treatment effect on cause k
- ▶ Analysis completely standard
- ▶ But effect of covariate on cumulative incidence sometimes unexpected (because it depends on the competing hazards as well)!

Regression on cumulative incidence function

- ▶ Define **subdistribution hazard**

$$\bar{\lambda}_k(t) = -\frac{d \log(1 - I_k(t))}{dt}.$$

- ▶ Impose proportional hazards assumption on the subdistribution hazard instead of on cause-specific hazard [Fine & Gray, 1999]

$$\bar{\lambda}_k(t | Z) = \bar{\lambda}_{k,0}(t) \exp(\beta_k Z).$$

- ▶ This does imply expected relation

Regression results

	Death due to gastric cancer		Death due to other causes	
	Coef (SE)	P-value	Coef (SE)	P-value
Cause-specific hazards	-0.18 (0.12)	0.12	0.25 (0.16)	0.12
Fine-Gray	-0.27 (0.12)	0.021	0.31 (0.16)	0.055
Gray log-rank		0.021		0.061

- ▶ Cause-specific hazard ratios of D2 with respect to D1
 - ▶ Gastric cancer: $HR_1 = 0.83$
 - ▶ Other causes: $HR_2 = 1.28$

Back to overall survival

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 - ▶ D2-dissection: $\lambda_{\bullet,D2}(t) = \lambda_{1,0}(t)HR_1 + \lambda_{2,0}(t)HR_2$
- ▶ Relative hazard for D1:

$$\pi_{1,D1}(t) = \frac{\lambda_{1,0}(t)}{\lambda_{1,0}(t) + \lambda_{2,0}(t)} = 1 - \pi_{2,D1}(t)$$

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- ▶ Hazard ratio D2 with respect to D1 for overall survival

$$\begin{aligned} HR(t) &= \frac{\lambda_{\bullet,D2}(t)}{\lambda_{\bullet,D1}(t)} = \frac{\lambda_{1,0}(t)HR_1 + \lambda_{2,0}(t)HR_2}{\lambda_{1,0}(t) + \lambda_{2,0}(t)} \\ &= \pi_{1,D1}(t)HR_1 + (1 - \pi_{1,D1}(t))HR_2 \end{aligned}$$

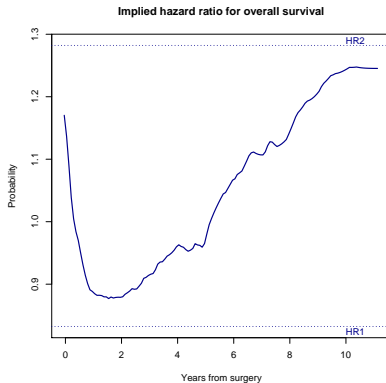
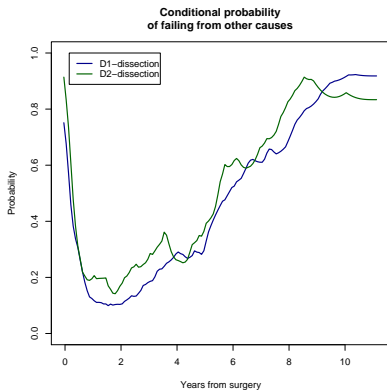
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 HR(t) &= \frac{\lambda_{\bullet,D2}(t)}{\lambda_{\bullet,D1}(t)} = \frac{\lambda_{1,0}(t)HR_1 + \lambda_{2,0}(t)HR_2}{\lambda_{1,0}(t) + \lambda_{2,0}(t)} \\
 &= \pi_{1,D1}(t)HR_1 + (1 - \pi_{1,D1}(t))HR_2 \\
 \text{(or)} &= \pi_{2,D1}(t)HR_2 + (1 - \pi_{2,D1}(t))HR_1
 \end{aligned}$$

Relative hazards



Modeling approaches

- ▶ Let's see if we can use the concepts of total and relative hazards in a model
- ▶ Regression on cause-specific hazards models effect of treatment for each cause separately
- ▶ This is an indirect, but convenient way of modeling the joint distribution, $P(T, D)$, of time and cause of failure (recall, $I_k(t) = P(T \leq t, D = k)$)
- ▶ Other approaches
 - ▶ $P(T, D) = P(D) \cdot P(T | D)$ [Larson & Dinse, 1985], mixture model

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- ▶ Other approaches
 - ▶ $P(T, D) = P(D) \cdot P(T | D)$ [Larson & Dinse, 1985], mixture model
 - ▶ $P(T, D) = P(T) \cdot P(D | T)$, selection model, cause of failure model

Cause of failure model

- ▶ Model for $P(T)$: for instance (but not necessarily) proportional hazards model
- ▶ Model for $P(D | T = t)$: logistic (general polytomous) regression with treatment and time-effects
- ▶ Two approaches:
 - ▶ Logistic regression model for D1- and D2-dissection separately, with smoothed time-effects
 - ▶ Logistic regression model with treatment, $f(t)$, and interaction

Cumulative incidence functions

- ▶ How do we get the cumulative incidence functions back?
- ▶ Remember we have model for total hazard, and hence we have an estimate of $\exp(-\Lambda_{\bullet}(t))$
- ▶ Now we have

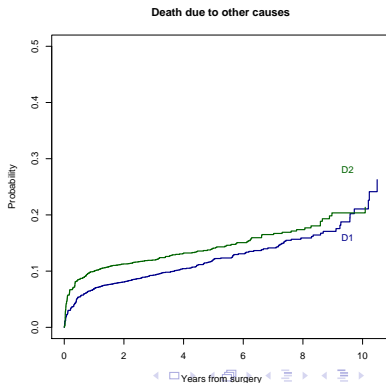
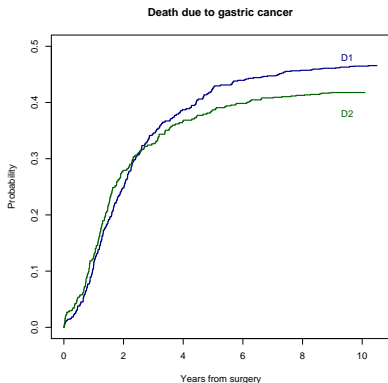
$$\lambda_1(t) = \pi_1(t) \lambda_{\bullet}(t)$$

- ▶ Hence

$$\begin{aligned} I_1(t) &= \int_0^t \lambda_1(s) \exp(-\Lambda_{\bullet}(s)) ds \\ &= \int_0^t \pi_1(s) \lambda_{\bullet}(s) \exp(-\Lambda_{\bullet}(s)) ds \\ &= \int_0^t \pi_1(s) f_{\bullet}(s) ds \end{aligned}$$

Resulting cumulative incidence curves

- ▶ Based on
 - ▶ Separate logistic regression models for D1 and D2 with smoothed time effects
 - ▶ Separate Kaplan-Meier estimates for D1 and D2



Discussion

- ▶ Competing risks with different cause-specific treatment effects can explain time-dependent effects
 - ▶ Overall hazard ratio is weighted mean of cause-specific hazard ratios, weights given by relative hazards
- ▶ Mixture model:
 - ▶ Suggests that cause of failure is determined from the outset
 - ▶ Typically need EM-algorithm for estimation
 - ▶ Results depend on follow-up
- ▶ Selection model, cause of failure model:
 - ▶ Useful alternative to proportional cause-specific or subdistribution hazards model
 - ▶ Straightforward to program, but may need smoothing of $P(D = d | T = t)$ as function of t
 - ▶ Can incorporate missing cause of failure

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